INTERNATIONAL STANDARD

ISO 7176-22

> Second edition 2014-09-01

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Set-up procedures
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Partie 22: Procédures

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2. www.iso.org/directives

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received. www.iso.org/patents

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the WTO principles in the Technical Barriers to Trade (TBT), see the following URL: Foreword - Supplementary information

The committee responsible for this document is ISO/TC 173, *Assistive products for persons with disability*, Subcommittee SC 1, *Wheelchairs*.

Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

This second edition cancels and replaces the first edition (ISO 7176-22:2000), all clauses of which have been technically revised.

ISO 7176 consists of the following parts under the general title *Wheelchairs*:

- Part 1: Determination of static stability
- Part 2: Determination of dynamic stability of electric wheelchairs
- Part 3: Determination of effectiveness of brakes
- Part 4: Energy consumption of electric wheelchairs and scooters for determination of theoretical distance range
- Part 5: Determination of dimensions, mass and manoeuvring space
- Part 6: Determination of maximum speed, acceleration and deceleration of electric wheelchairs
- Part 7: Measurement of seating and wheel dimensions
- Part 8: Requirements and test methods for static, impact and fatigue strengths
- Part 9: Climatic tests for electric wheelchairs
- Part 10: Determination of obstacle-climbing ability of electrically powered wheelchairs
- Part 11: Test dummies

- Part 13: Determination of coefficient of friction of test surfaces
- Part 14: Power and control systems for electrically powered wheelchairs and scooters Requirements and test methods
- Part 15: Requirements for information disclosure, documentation and labelling
- Part 16: Resistance to ignition of postural support devices
- Part 19: Wheeled mobility devices for use as seats in motor vehicles
- Part 21: Requirements and test methods for electromagnetic compatibility of electrically powered wheelchairs and scooters, and battery chargers
- Part 22: Set-up procedures
- Part 25: Batteries and chargers for powered wheelchairs
- Part 26: Vocabulary
- Part 28: Requirements and test methods for stair-climbing devices

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Introduction

Many wheelchairs have adjustable or optional features, which, depending upon their setting, can have significant effects on the results from test methods in different wheelchair testing standards.

When used in combination with other wheelchair standards the procedure presented within this standard will produce test results which permit comparison between different wheelchairs and give comparable results between different test laboratories.

If a wheelchair is configured in a specific way, some clauses of ISO 7176-22 might not apply.

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Wheelchairs —

Part 22:

Set-up procedures

1 Scope

This part of ISO 7176 specifies a set-up procedure to be used as a part of the preparation of adjustable wheelchairs for testing. This procedure takes the manufacturer's instructions into account.

This part of ISO 7176 is applicable to manual wheelchairs and electric wheelchairs (including scooters) intended to provide indoor and/or outdoor mobility.

NOTE Other parts of ISO 7176 may have specific requirements for the adjustment of the wheelchair. In such cases, the individual part of ISO 7176 takes precedence over this part of ISO 7176.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 7176-11, Wheelchairs — Part 11: Test dummies

ISO 7176-26, Wheelchairs — Part 26: Vocabular)

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 7176-26 apply.

- 4 Test apparatus
- **4.1 Test dummy**, as specified in ISO 7176-11.
- **4.2 Means for measuring linear dimensions up to 2 000 mm**, to an accuracy of ±1 mm.
- 4.3 Means for measuring the angles of surfaces to each other and/or to vertical or horizontal, to an accuracy of $\pm 0.2^{\circ}$.
- **4.4** Means of measuring forces, between 25 N and 250 N to an accuracy of ±5 % of the measurement
- **4.5 Means of measuring torque**, between 2 Nm and 100 Nm to an accuracy of ±10 % of the measurement.
- **4.6 Means to inflate pneumatic wheelchair tyres**, up to 10 bar with an accuracy of ± 0.2 bar.
- **4.7 A hard horizontal test plane**, of sufficient size to support the wheelchair during testing, such that the whole surface is contained between two imaginary parallel planes 5 mm apart.

NOTE The imaginary planes are intended to provide a measure of control on the flatness of the test plane.

4.8 Means to secure the torso and thigh segment of the test dummy, so that the dummy will remain in the intended position, without deformation of the wheelchair or the dummy.

It is important that the means do not prevent rotation of the hip, knee and ankle pivot.

Straps made of Nylon webbing of sufficient strength may be used.

NOTE For some designs of wheelchairs, care is needed to avoid bending the tubes of the back support towards each other.

4.9 Means to secure the feet of the test dummy to the foot supports, so that they will remain in the intended position, without deformation of the wheelchair or dummy.

It is important that the means do not affect the strength of the foot support(s).

The feet of the test dummy may be clamped to the foot support(s) of the wheelchair, or holes may be drilled no greater than 8 mm in diameter and the feet bolted in position, providing the strength of the foot support(s) is not affected.

5 Set-up levels

Other documents that refer to the set-up procedures specified in this document may use or modify parts of the set up procedure contained within this standard according to their own purposes. Other test standards may reference a limited number of the requirements of this standard. This standard provides specific set-up information in 6.2.2 and 6.2.3. The different test standards may choose a set of setup requirements from this standard based on the three set-up levels specified in 6.2.2, 6.2.3 and in 6.2.2 and 6.2.3 shall be used if there is no reference to another set-up level (see 6.2.3) or subset of requirements within a specific test standard.

The Reference set-up tables contained in this standard each contain three different occupant mass groups, less than $50\,\mathrm{kg}$, $50\,\mathrm{kg}$ to $125\,\mathrm{kg}$ and more than $125\,\mathrm{kg}$. Use the maximum occupant mass specified by the manufacturer to determine the occupant mass group.

Reference set-up tables for set-up level 1 and set-up level 2 are presented in Annex C.

NOTE Guidance for wheelchair selection is presented in Annex D.

6 Preparation of the test wheelchair

6.1 Wheelchair equipment

Where a particular standard specifies equipment to be fitted to the wheelchair, use the equipment specified in that particular part. All other equipment shall be used in accordance with this subclause.

Unless specified otherwise in this document or by those commissioning the tests and unless noted in the test report the wheelchair shall be complete and ready for use. It shall comprise all following components or parts, where applicable: seat, back support, arm supports, lower leg support assemblies, posterior lower leg supports, posterior foot supports, frame, wheels, hand rims, motors and drive trains, braking system, battery sets, controllers, steering mechanisms, push handle(s), anti-tip devices, curb-climbing device.

NOTE 1 Some tests can require a part of a wheelchair to be dismantled.

Unless they are an integral part of the wheelchair, or necessary for the successful conduct of a test, the following components or parts, including the means to connect them to the wheelchair, shall be removed:

cushions,

- postural support device components such as head supports, lateral trunk supports etc.,
- storage unit such as baskets, backpacks, transfusion containers, urine collection bags and oxygen bottles.

NOTE 2 A component or part that is supplied with the wheelchair and is removable but fixed with hook and loop fastener is not deemed an integral part.

Where a support surface would not normally be used without a cushion (e.g. a solid ply seat support base), an appropriate cushion, such as one provided by the wheelchair manufacturer, should be fitted to the wheelchair.

NOTE 3 For specific tests there are exclusions from this statement (see NOTE in 8.5).

6.2 Wheelchair adjustment

6.2.1 General

This standard shall take precedence in setting up a wheelchair in readiness for testing except:

- when a particular test standard has specific adjustment requirements, then the adjustment procedure specified in that particular standard shall be used. All other adjustments not specified in that standard shall be made in accordance with this subclause.
- when the manufacturer specifies particular requirements or limitations to the setup, then such variations shall be followed to the extent necessary, and such variations used shall be detailed in the test report.

Set-up can be done in any order that is most practicable for each part of ISO 7176.

If the seat is capable of swivelling to more than one position around the vertical axis (e.g. in a scooter), adjust the seat to the forward facing position, so that the longitudinal axis of the seat is parallel to the longitudinal axis of the wheelchair with an accuracy of $\pm 2^{\circ}$. If this position or accuracy is not achievable set the axes as close as possible and document the variation in the test report.

If the seat can be attached in a forward or rearward facing position, attach the seat to the default position specified by the manufacturer, or, where there is no such specification attach it so that the wheelchair has a rear wheel drive.

In the case of an adjustable component with no defined greatest and or smallest position or dimension, the mid position shall be half way between the position fully contracted or inserted and the position fully extended or expanded.

If the wheelchair has pneumatic tyres, inflate them to the pressure recommended by the wheelchair manufacturer. If a pressure range is given, inflate to the highest pressure in the range. If there is no recommendation for inflation pressure from the wheelchair manufacturer, inflate the tyres to the maximum pressure recommended by the tyre manufacturer.

If head supports are an integral part of the body support system and are adjustable in height, the "head support height above seat" shall be set to (680 ± 5) mm for occupant mass group I and (780 ± 5) mm for occupant mass group II and III. If this is not possible set it as close as possible to the reference value.

If the characteristics of wheel suspensions can be adjusted, adjust them to the default setting specified by the manufacturer, or, where there is no such specification adjust it so that the wheelchair has the shortest and hardest spring suspension.

Adjust the brakes in accordance with Annex A.

Record all adjustments in accordance with <u>Annex B</u>.

6.2.2 Wheelchairs with handrims

NOTE 1 Wheelchairs with handrims include wheelchairs with manual handrim propulsion and handrim activated power assisted wheelchairs (HAPAW).

Set any adjustable dimensions of the wheelchair to the reference set-up values specified in <u>Table 1</u>, with an accuracy of ± 3 mm for longitudinal dimensions or $\pm 1^{\circ}$ for angular dimensions, except where otherwise stated. If this is not possible set it as close as possible to the reference value.

If the reference set-up value is not available/possible (e.g. the two nearest positions are centred above and below the reference set-up value with equal distance), give preference to the next smaller value.

NOTE 2 An active wheelchair might not have castor sizes as indicated in <u>Table 1</u>.

Adjust the anti-tip devices (where applicable) to the following position:

- Set the rising to (25 ± 3) mm (see ISO 7176-5).
- When the wheelchair is standing on level ground the anti-tippers protrude to the rear as far as possible.
- If it is not possible to achieve both settings at one time, give priority to the setting of the rising.
- If this is not possible set it as close as possible to the reference value.
- If the manufacturer recommends more than one setting, use the recommended setting closest to these default settings.

If any of the adjustments results in an unwanted setting, e.g. the castor wheels contact any other part of the wheelchair, increase/decrease the adjustment just enough to ensure a proper function of the wheelchair and record the actual dimension together with the reason in accordance with Annex B.

Table 1 — Reference set-up values for wheelchairs with handrims (LEVEL 3)

Item	Refe	rence set-up v	alues
Click	Occupant mass group I	Occupant mass group	Occupant mass group III
	(<50 kg)	II	(>125 kg)
CON		(50 kg to 125 kg)	
Properties for seating and ergono	mics (see NOTE	E 1)	
Seat plane angle	4°	4°	4°
Effective seat depth	340	450	450
Effective seat width	In accorda	nce with formu	la in NOTE 2
Seat surface height at front edge	470	520	520

NOTE 1 All dimensions in millimetres unless otherwise indicated.

NOTE 2 For the purpose of establishing the reference value for the effective seat width or back support width use the formula:

$$W = 42 \times \sqrt{M_{\rm O}} + 35$$

where

W is the desired width (effective seat width or back support width);

 M_0 is the maximum occupant mass (kg).

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

NOTE 4 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

NOTE 5 If a set value is in conflict with the test, adjust to closest setting not to interfere.

Table 1 (continued)

Item	Item Reference set-up values		alues
	Occupant mass group I	Occupant mass group	Occupant mass group III
	(<50 kg)	II	(>125 kg)
		(50 kg to 125 kg)	
Back support angle	10°	10°	10°
Back support height	340	420	420
Handgrip height	820	950	950
Back support width	In accorda	nce with formu	la in NOTE 2
Foot support to seat	340	450	450
The foot support clearance shall not be less than.	50	40	40
Foot support length	150	150	150
Foot support to leg angle	90° C	90°	90°
Leg to seat surface angle	908	97°	97°
Arm support height	160	200	200
Front of arm support to back support	200	320	320
Handrim diameter	490	530	530
Manoeuvring wheels, diameter	560	610	610
Wheelbase	340	400	400
Camber	-3°	0°	0°
Manoeuvring wheels, horizontal position	20	20	20
Manoeuvring wheels, vertical position	166	184	184
Castor wheels, diameter	150	175	175
Properties of the chassis (s	ee NOTE 3)		
Manoeuvring wheels, track	mid-position (see NOTE 4)		
Castor wheels, track	mid-position (see NOTE 4)		
Castor stem housings, horizontal position mid-position (see NOTE 4)		OTE 4)	
Castor stem housings vertical position mid-position (see NOTE 4)		OTE 4)	
Castor wheel axle vertical position in fork mid-position (see NOTE 4)		OTE 4)	
Castor rake 0° +1° / -0°			

NOTE 1 All dimensions in millimetres unless otherwise indicated.

NOTE 2 For the purpose of establishing the reference value for the effective seat width or back support width use the formula.

$$W = 42 \times \sqrt{M_{\rm O}} + 35$$

where

W is the desired width (effective seat width or back support width);

 M_0 is the maximum occupant mass (kg).

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

NOTE 4 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

NOTE 5 If a set value is in conflict with the test, adjust to closest setting not to interfere.

Table 1 (continued)

Item	Reference set-up values		alues
	Occupant mass group I	Occupant mass group	Occupant mass group III
	(<50 kg)	II	(>125 kg)
		(50 kg to 125 kg)	
Castor cant	0° ± 0,5°		
Castor trail	50		

NOTE 1 All dimensions in millimetres unless otherwise indicated.

NOTE 2 For the purpose of establishing the reference value for the effective seat width or back support width use the formula:

$$W = 42 \times \sqrt{M_{\odot}} + 35$$

where

W is the desired width (effective seat width or back support width);

 M_0 is the maximum occupant mass (kg).

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

NOTE 4 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

NOTE 5 If a set value is in conflict with the test, adjust to closest setting not to interfere.

6.2.3 Wheelchairs without handrims

NOTE Wheelchairs without handrims include electrically powered wheelchairs, manual wheelchairs with lever propulsion and push wheelchairs.

Set any adjustable dimensions of the wheelchair to the reference set-up values specified in <u>Table 2</u>, with an accuracy of ± 3 mm for longitudinal dimensions or $\pm 1^{\circ}$ for angular dimensions respectively, except where otherwise stated. If this is not possible set it as close as possible to the reference value.

If the reference set-up value is not available/possible (e.g. the two nearest positions are centred above and below the reference set-up value with equal distance), give preference to the next smaller value.

Adjust the anti-tip devices (where applicable) as close as possible to the following position.

- Set the rising to (50 ± 3) mm (see ISO 7176-5).
- When the wheelchair is standing on level ground the anti-tippers protrude to the rear as far as possible.
- If it is not possible to achieve both settings at one time, give priority to the setting of the rising.
- If this is not possible set it as close as possible to the reference value.
- If the manufacturer recommends more than one setting, use the recommended setting closest to the default setting.

Adjust any kerb-climbing devices to their working position as recommended by the manufacturer.

If the wheelchair has a tiller, adjust the horizontal distance between the tiller and the back support as recommended by the manufacturer. If there is no recommendation, adjust to (460 \pm 25) mm for wheelchairs intended for occupant mass group I and (640 \pm 25) mm for wheelchairs intended for occupant mass group II or III. If this is not possible set it as close as possible to the reference value.

If more than one setting is recommended, use the recommended setting that is closest to these preferred settings.

If any of the adjustments results in an unwanted setting, e.g. the wheels contacting any other part of the wheelchair, increase/decrease the adjustment just enough to ensure a proper function of the wheelchair and record the actual dimension together with the reason in accordance with Annex B.

Table 2 — Reference set-up values for wheelchairs without handrims (LEVEL 3)

Item	Reference set-up values		
	Occupant mass group	Occupant mass group	Occupant mass group
	I	и о	III
	(<50 kg)	(50 kg to 125 kg)	(>125 kg)
Properties for seating and ergonon	nics (see NOTE	1)	
Seat plane angle	4°	4°	4°
Effective seat depth	340	450	450
Effective seat width	Inaccordan	ce with formula	a in NOTE 2
Seat surface height at front edge	470	520	520
Back support angle	10°	10°	10°
Back support height	400	500	500
Handgrip height	820	950	950
Back support width	In accordan	ce with formula	a in NOTE 2
Foot support to seat	340	450	450
BUT NO LESS THAN: Foot support clearance	50	40	40
Foot support length	150	150	150
Foot support to leg angle	90°	90°	90°
Leg to seat surface angle	90°	97°	97°
Arm support height	160	200	200
Front of arm support to back support	200	320	320
Properties of the chassis (se	e NOTE 3)		
Fixed wheels, diameter	1	argest diamete	ſ
Fixed wheels, horizontal position	mid-p	osition (see NO	TE 4)
Fixed wheels, vertical position	mid-position (see NOTE 4)		
Fixed wheels, camber		0°	
NOTE All discourses in monada and analysis discourse			

NOTE 1 All dimensions in mm unless otherwise indicated.

NOTE 2 For the purpose of establishing the reference value for the effective seat width or back support width use the formula:

$$W = 42 \times \sqrt{M_{\rm O}} + 55$$

where

W is the desired width (effective seat width or back support width);

 M_0 is the maximum occupant mass (kg).

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

NOTE 4 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

Table 2 (continued)

Item	Refe	rence set-up va	alues	
	Occupant mass group	Occupant mass group	Occupant mass group	
	I	II	III	
	(<50 kg)	(50 kg to 125 kg)	(>125 kg)	
Fixed wheels, track mid-position (see NOTE 4)		TE 4)		
Movable wheels, diameter	largest diameter			
Movable wheels, horizontal position	mid-p	mid-position (see NOTE 4)		
Movable wheels, vertical position	mid-position (see NOTE 4)			
Movable wheels, track	mid-position (see NOTE 4)			
Movable wheel axles, vertical position in fork	mid-position (see NOTE 4)			
Castor rake (where applicable)	0° +1°), -0°			
Castor cant (where applicable)	29° ± 0,5°			
Castor trail (where applicable)		50		

NOTE 1 All dimensions in mm unless otherwise indicated.

NOTE 2 For the purpose of establishing the reference value for the effective seat width or back support width use the formula:

$$W = 42 \times \sqrt{M_{\odot}} + 55$$

where

W is the desired width (effective seat width or back support width);

 M_0 is the maximum occupant mass (kg).

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

NOTE 4 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

6.2.4 Electrical equipment

6.2.4.1 Batteries

Where a manufacturer specifies more than one battery set, the heaviest battery set recommended should be fitted.

Charge the batteries to at least 75 % of their rated nominal capacity.

NOTE Some tests can require a different amount of charge.

If, for a given test, it is recommended to replace the battery by a substitute mass in order to prevent spilling of battery acid, a substitute mass shall be used with the same dimensions, mass and location of centre of mass.

WARNING — If the wheelchair is equipped with free-electrolyte-type batteries, some tests can be hazardous due to the risk of spillage. In such cases, the batteries may be replaced with the closest non-spillable batteries, using supplementary weights to provide equivalent mass distribution where necessary.

6.2.4.2 Position of the control device

For electrically powered wheelchairs with a control device that can be placed in different positions in the lateral direction, set it to the mid-position. Where there is no provision for this position, use the position that gives the mid-setting nearest to the axis centreline of the arm support.

If the control device can be placed in different positions in the fore-aft direction, set it to 450 mm for occupant mass group I and 540 mm for occupant mass group II and III in front of the back support with an accuracy of $\pm 3 \text{ mm}$. If this is not possible set it as close as possible to the reference value.

If the control device can be placed at different heights, set its lever top to 40 mm above the armrest with an accuracy of $\pm 3 \text{ mm}$. If this is not possible set it as close as possible to the reference value.

6.2.4.3 Operator adjustable electrical settings

Set all operator-accessible adjustments that affect the response of the wheelchair, such as the maximum speed control, sensitivity and other user-adjustable settings for maximum response. Record the settings in accordance with Annex B.

EXAMPLE Maximum forward speed, maximum reverse speed, maximum sensitivity, maximum acceleration, maximum deceleration, maximum braking and minimum time delay.

6.2.4.4 Adjustable electrical control devices

Set any other adjustable electrical control devices, adjustments of which do not require the use of tools, to the manufacturer's recommended setting. If there is no recommended setting for any such controls, set them to the mid-setting.

- NOTE 1 There can be different settings for the same wheelchairs depending on the drive mode.
- NOTE 2 There can also be specific settings for individual tests in different parts of ISO 7176.

6.2.5 Other adjustable components

Set mechanically adjustable components of the wheelchair, which are not covered by <u>Tables 1</u> and <u>2</u> respectively as close as possible to the mid-position of their range with an accuracy of ±3 mm. If this is not possible (e.g. there is no adjustment point at the mid-position or there are only two positions), set to the position next smaller than the mid-position

7 Final adjustments

After completing the requirements in <u>Clause 6</u>, make the following final adjustments with priority given to those last in the list, but not in conflict with the manufacturer's instructions.

If the dimensions of <u>Tables 1</u> and <u>2</u> are not available or possible, adjust the dimension as close as possible to the reference set-up value. If this is not possible, set to the position next smaller than the mid-position.

Make every effort to minimize castor shimmy during test performances. There may be several ways of doing this including adjusting castor rake and castor cant.

If the parking brakes are adjustable, adjust the parking brakes as specified by the manufacturer. If there are no manufacturer's specifications, adjust the brakes in accordance with the measurements taken in Annex A.

Ensure that all fasteners disturbed during adjustment are tightened in accordance with the manufacturer's recommendations. If there are no manufacturer's recommendations, tighten in accordance with Annex A.

8 Loading of the wheelchair

8.1 General

Where the referring document specifies a load for the wheelchair other than those specified in this document, select, fit and restrain the load as specified in the referring document.

If the referring document requires the use of a test dummy as specified in ISO 7176-11, follow the procedure specified in 8.2. If the referring document requires the test dummy to be restrained, follow the procedure specified in 8.3.

If the referring document specifies a human test occupant, follow the procedure specified in 8.4.

8.2 Test dummy

WARNING — Take care when handling the test dummy, as it can be very heavy.

Where a referring document specifies a method for selecting and positioning the test dummy, select and position the test dummy as specified in that document. Otherwise use the following method.

Use the following procedure for selecting and positioning the dummy.

a) Measure the actual seat plane angle and the actual back support angle that result from the final adjustments in <u>Clause 7</u>. Calculate the angle between the seat plane and the back support as follows:

$$A = 90 + B - S$$

where

- A is the angle between seat plane and back support plane;
- *B* is the back support angle:
- *S* is the seat plane angle.

Then record the result, in degrees

b) Select a test dummy including loading plates of mass equal to the maximum occupant mass that is specified by the manufacturer. Consider the mass of any other accessories that is included in the rated load of the wheelchair.

Select a thigh loading plate according to ISO 7176-11 that will fill as much of the seat support surface of the wheelchair as possible with a minimum clearance of 12 mm between the edge of the thigh loading plate and anything adjacent to the thigh loading plate. If the wheelchair has sling type seat, the thigh loading plate must not rest on the seat rails of the wheelchair. To prevent unnatural loading of the upholstery, the thigh loading plate must sit inside of the seat rails of the wheelchair. If the loading plate specified in ISO 7176-11 is too big select the next smallest specified in ISO 7176-11.

Select a torso loading plate that will fill as much of the back support of the wheelchair as possible with a minimum clearance of 12 mm between the edge of the torso loading plate and anything adjacent to the torso loading plate. If the wheelchair has sling type backrest, the torso loading plate must not rest on the back support frame members of the wheelchair. To prevent unnatural loading of the upholstery, the torso loading plate must sit inside of the back support frame members of the wheelchair. If the loading plate specified in ISO 7176-11 is too big select the next smallest specified in ISO 7176-11.

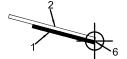
Attach the loading plates to the test dummy in accordance with ISO 7176-11 and record the mass of the dummy and the sizes of the loading plates used.

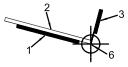
- c) If there is a tiller, take 5 % of the mass from the test dummy torso and add it evenly over the two handles of the tiller. Adjust the tiller to keep it straight during the test.
- d) Place the selected test dummy in the wheelchair.
- e) Position the dummy symmetrically with a tolerance of ± 10 mm about the wheelchair reference plane.
- f) Ensure that the hip pivots between the torso segment and thighs segment of the dummy rotate freely.
- g) Adjust the fore-aft position of the dummy to give an angle between the seat plane and the back support plane within ±3° of angle A (as determined in a).

NOTE If the dummy has to be removed from the wheelchair during the test procedure and then be replaced, a reference mark on the wheelchair frame, perpendicular to the dummy hip pivot point, can be used to aid rapid replacement.

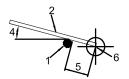
- h) Perform the positioning of the feet of the test dummy as follows.
 - If the wheelchair has two separate foot supports, position the dummy's foot loading pads in a
 direction parallel and centrally on each foot support, viewed from the side of the wheelchair.
 - If the wheelchair has a one piece foot support, position the dummy's foot loading pads in a direction parallel to and at a distance of (100 ± 20) mm to both sides of the centre line of the foot support seen from the sideways direction of the wheelchair.
 - Position the dummy's foot loading pads on the foot supports in the fore/aft direction as specified
 in Figure 1. If this position of the feet of the test dummy is not possible or if there is an indication
 that it would give an unrealistic seating position for a human test occupant, correct to a possible
 and realistic position and record the position and reason why it was necessary
 - In case of tubular foot supports align the dummy's foot loading pads at $(15 \pm 1)^\circ$ to the horizontal (front upwards)
 - When the test dummy is installed in the wheelchair, the distance from the knee pivot to the ankle pivot shall be locked after the lower legs segment is placed with its weight supported solely by the foot supports.
- If the foot support clearance becomes less than 50 mm for occupant mass group I and less than 40 mm for occupant mass group II or III when the foot supports are loaded, adjust the foot support to seat distance so that the applicable minimum is achieved.

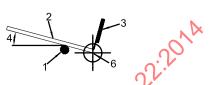
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a) Flat foot support without posterior heel support with posterior heel support port





c) Tubular foot support without posterior heel d) Tubular foot support with posterior heel support

Key

- 1 foot support
- 2 dummy's foot loading pad
- 3 posterior lower leg support or posterior foot support
- 4 $(15 \pm 1)^{\circ}$
- 5 (63 \pm 5) mm for occupant mass group I and (100 \pm 5) mm for occupant mass group II and III
- 6 alignment point

Figure 1 — Position of the dummy's feet on various foot supports

8.3 Test dummy securement

Where the referring document specifies a method for restraining the test dummy, restrain the test dummy, as specified in that document. Otherwise, secure the segments of the test dummy, using the means specified in 4.8 and 4.9, so that the segments retain the position specified in 8.2.

8.4 Human test occupant

Where a referring document specifies a method for selecting and positioning the human test occupant, select and position the human test occupant as specified in that document. Otherwise use a human test occupant with supplementary weights, weighted garments and spacers as applicable, to give a mass and mass distribution equivalent to the applicable dummy when assessed in accordance with ISO 7176-11.

It is preferable that the proportion of the supplementary weights does not exceed 10 % of the applicable test dummy mass.

WARNING — It is essential that appropriate precautions be taken to ensure the test personnel's safety.

8.5 Accessories that contribute to the rated load

For some specific tests the following items can be used at the discretion of the commissioner of the test.

EXAMPLE Specific tests (tests under worst case conditions) can be in ISO 7176-1, ISO 7176-2, ISO 7176-3, ISO 7176-6, ISO 7176-8 and ISO 7176-10 (static and dynamic stability, brakes, speed, strength and obstacle climbing).

NOTE This subclause gives an exclusion from a general statement (see NOTE 2 in 6.1).

When the wheelchair is delivered with a storage unit (e.g. basket), or the manufacturer specifies that it is intended/permitted to carry storage units on the wheelchair, fix the storage unit to the wheelchair and load it with a mass as specified by the manufacturer or if there is no such specification, load it with a mass of 7 kg.

When the manufacturer specifies that it is intended or permitted to carry a backpack on the wheelchair, make provision to load the wheelchair with a substitute backpack in accordance with the manufacturers specification. If there is no such specification, hang a mass of 7 kg from the backpack carrier or, when there is no carrier specified, hang a mass of 7 kg from the back support at the most convenient location (e.g. handgrips or top of back support), so that its centre of mass is (300 ± 20) mm below the point of attachment.

When the manufacturer specifies that it is intended/permitted to carry transfusion containers or urine collection bags etc. on the wheelchair, fix the item on the wheelchair as specified by the manufacturer and load it with a mass as specified by the manufacturer or if there is no such specification, with a mass of (2 ± 0.1) kg.

When the manufacturer specifies that it is intended/permitted to carry an oxygen bottle on the wheelchair, fix the bottle to the wheelchair as specified by the manufacturer and load it with a mass as specified by the manufacturer or if there is no such specification, load it with a mass of (7 ± 0.1) kg.

All options shall lie within the limits recommended by the manufacturer.

When the manufacturer specifies any accessories the total allowable mass stated by the manufacturer shall still be within stated limits of the maximum occupant mass that is specified by the manufacturer.

9 Records

Record all equipment fitted, added or removed in accordance with Annex B.

Record adjustments and loading settings of the test wheelchair (<u>Clauses 6</u> to <u>9</u>).

Record any deviation from the specifications in <u>Clauses 6</u> to <u>9</u> and reasons for deviation in accordance with <u>Annex B</u>.

Record any options selected, and justifications for selecting them.

NOTE A template for the records is given in <u>Annex B</u>.

Annex A

(normative)

Wheelchair brakes and fasteners

Adjust the brakes so that:

- where the manufacturer's instructions for use specify the method for adjustment of the brakes, adjust the brakes in accordance with those instructions;
- if there are no specifications adjust the brakes so that the operating forces lie within the ranges specified in <u>Table A.1</u>;
- where brakes cannot be adjusted to give operating forces as specified in <u>Table A.N.</u>; adjust the brakes so that the operating forces are as close as possible to those in <u>Table A.1</u>.

For scooters, <u>Table A.1</u> applies only to adjustment of means to operate parking brakes.

Table A.1 — Operating forces

Means of operation	Operating force
hand/arm operation ^a	60 ± 5
foot, push	100 ± 10
foot, pull	60 ± 5
finger	5 ± 1
handb	13,5 ± 2

a An operation where the strength of the combined hand and arm can be used.

The operating forces are derived from ISO 9355-3 where maximum recommended force for a normal adult is given, considering the direction of force applied.

Adjustable components are normally located and retained by knobs, hand wheels, levers and bolts.

If the manufacturer has not specified torque figures, <u>Table A.2</u> gives guidance for torque settings for particular types.

b An operation where only the strength of a single hand can be used, that can include two or more fingers.

Table A.2 — Maximum torque settings

Fastener	Dimension	Maximum torque
	mm	Nm
Turning knobs or hand wheels oper-	<i>D</i> ≤ 25	$T = D \times 0,025$
ated by one hand	D > 25	(where <i>D</i> is the knob overall diameter in mm)
		$T = D \times 0.05$
		(where <i>D</i> is the knob overall diameter in mm)
Levers operated by one hand		$T = L \times 0,1$
Hexagon bolts and nuts	7 (M4)	18,
	8 (M5)	5,9
	10 (M6)	10
	13 (M8)	25
	17 (M10) 🏑 🔾	49
	19 (M12)	85

NOTE These values for tightening hexagon bolts and huts are based on a coefficient of friction of $\mu = 0,14$.

NOTE These values for tightening hexagon bolts and huts are based on a coefficient of friction of $\mu = 0,14$.

Annex B

(informative)

Record of the actual equipment, adjustments and loading settings

<u>Tables B.1</u> to <u>B.6</u> show records of actual equipment, adjustments and loading settings.

<u>Tables B.1</u> to <u>B.6</u> show records of actual equipment, adjustments and loading settings.					
Wheelchair identification (type, model, serial number etc.):					
Manufacturer:	Manufacturer:				
Address:		and the second			
Type class (A, B or C):		1/10			
Rated load and/or maximum occu	pant mass:	col			
Drive wheel position (rear, front o	r mid):				
	Table B.1 — Actual equipmen	tok of 150 1/10-2:201A			
Equipment	Type of equipment	Value/Position/Measure			
	(Size, article number etc)				
Body support system					
Seat	ilen				
Back support	*0				
Head support					
Cushion	Clie				
Wheel suspensions					
Tyres	cOp.				
Braking system					
Motor					
Batteries					
Storage unit (f.i. basket)					
Backpack carrier or permission					
Oxygen bottle carrier					
Transfusion container carrier					
Urine collection bag carrier					
NOTE Cite NA for items that are not ac					

Table B.2 — Actual dimensions for seating and ergonomics

Adjustable part	Type of equipment	Value/Position/Measure	
	(Size, article number etc.)		
Seat plane angle			
Effective seat depth			
NOTE Cite NA for items that are not adjustable or applicable.			

Table B.2 (continued)

	Adjustable part	Type of equipment	Value/Position/Measure
		(Size, article number etc.)	
Effective seat width			
Seat surface	ce height at front edge		
Back supp	ort angle		
Back supp	ort height		
Handgrip l	height		
Back supp	ort width		
EITHER FO	ootrest to seat		
OR Foot su	ipport clearance		J
Foot suppo	ort length		16,
Foot suppo	ort to leg angle		1,
Leg to seat	t surface angle		CO
Arm suppo	ort height	<u> </u>	
Front of ar	m support to back support	√ O	
	Handrim diameter		
	Manoeuvring wheels, diameter	filler	
 Wheel-	Wheelbase	*100	
chairs with handrims	Camber	an .	
	Manoeuvring wheels, horizontal position	×0 ()	
	Manoeuvring wheels, vertical position	CK .	
	Castor wheels, diameter		
NOTE Cit	te NA for items that are not adjusta	ble or applicable.	

Table B.3 — Actual adjustments of the chassis

Adjustable part		Type of equipment	Value/Position/Measure		
	2	(Size, article number etc.)			
- KP	Manoeuvring wheels, track				
	Manoeuvring wheels, air pressure				
9	Castor wheels, track				
Wheel- chair with	Castor stem housings, horizontal position				
	Castor stem housings, vertical position				
	Castor wheel axle, vertical position in fork				
	Castor wheels, air pressure				
NOTE Ci	NOTE Cite NA for items that are not adjustable or applicable.				

Table B.3 (continued)

Adjustable part		Type of equipment	Value/Position/Measure
		(Size, article number etc.)	
	Fixed wheels, diameter		
	Fixed wheels, horizontal position		
	Fixed wheels, vertical position		
	Fixed wheels, camber		
	Fixed wheels, track		
Wheel-	Fixed wheels, air pressure		
chair without	Movable wheels, diameter		S. C.
handrims	Movable wheels, horizontal position		1/10
	Movable wheels, vertical position		(50)
	Movable wheels, track		10
	Movable wheel axles, vertical position in fork	, Q	$\mathcal{O}_{\mathbf{x}}$
	Movable wheel axles, air pressure	lu)	
Castor rak	re	'ille	
Castor can	t	ie ^W	
Castor tra	il	7,	
Anti-tip de	evice	4	
Kerb climber		ciic.	
Tiller distance to back support			
Other adjustable components		4,	
	etween the brake blocks and act surfaces		
NOTE Ci	te NA for items that are not adjusta	ble or applicable.	

${\bf Table~B.4-Actual~electrical~settings}$

Adjustable part	Type of equipment	Value/Position/Measure		
C/X	(Size, article number etc.)			
Batteries				
Position of the joystick				
Electrical settings				
Other electrical control devices				
Other adjustable components				
NOTE Cite NA for items that are not adjustable or applicable.				

Table B.5 — Final adjustment

Adjustable part	Type of equipment	Value/Position/Measure		
	(Size, article number etc.)			
Castor rake, left castor wheel (see NOTE 1)				
Castor rake, right castor wheel (see NOTE 1)				
Difference between left and right (see NOTE 1)				
Castor cant, left castor wheel (see NOTE 2)				
Castor cant, right castor wheel (see NOTE 2)		5. 		
Asymmetry between left and right (see NOTE 2)		176.		
Distance between the brake blocks and their contact surfaces				
NOTE 1 The measurement method is in ISO 7176-5, A.18. See also NOTE 1 in Clause 7.				
NOTE 2 The measurement method is in ISO 7176-5, A.19. See also NOTE 2 in Clause 7.				
NOTE 3 Cite NA for items that are not adjustable or applicable.				

Table B.6 — Loading of the wheelchair

Adjustable part	Type of equipment	Value/Position/Measure			
	(Size, article number etc.)				
Rated load OR	2,				
Maximum occupant mass	4				
Dummy size)*				
Torso loading plate					
Thighs loading plate					
Calculated seat-to-back angle (see <u>8.2</u> , a)					
Dummy's actual seat-to back angle					
Test dummy securement					
Human test occupant, mass + supplemental mass					
Accessory mass (see <u>8.5</u>)					
NOTE Cite NA for items that are not adjustable or applicable.					

Annex C

(normative)

Reference set-up values

<u>Tables C.1</u> to <u>C.4</u> give reference set-up values.

Table C.1 — Reference set-up values for wheelchairs with handrims (LEVEL 1)

Item	Reference set-up values			
	Occupant mass group I	Occupant mass group II	Occupant mass group	
	(<50 kg)	(50 kg to 125 kg)	(>125 kg)	
Properties of the chassis (see NOTE 1)				
Manoeuvring wheels, diameter	560	610	610	
Manoeuvring wheel, horizontal position	20	20	20	
Castor wheels, diameter	150	175	175	
Castor assembly, horizontal position	mid-position (see NOTE 2)			
Castor rake	0° +1° / -0°			
Castor cant	0° ± 0,5°			

NOTE 1 All dimensions in mm unless otherwise indicated

NOTE 2 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

NOTE 3 When any of these adjustments are inconflict with any seating adjustments, correct the setting to the minimum extent.

Table C.2 — Reference set-up values for wheelchairs with handrims (LEVEL 2)

Item	Reference set-up values		
	Occupant mass group	Occupant mass group	Occupant mass group
	I	II	III
	(<50 kg)	(50 to 125 kg)	(>125 kg)
Properties for seating and ergonon	nics (see NOTE	1)	
Seat plane angle	4°	4°	4°
Effective seat depth	340	450	450
Effective seat width	In accordar	ice with formula	a in NOTE 2
Seat surface height at front edge	470	520	520
Back support angle	10°	7C10°	10°
Back support height	340	420	420
Foot support to seat	340	450	450
BUT NO LESS THAN: Foot support clearance	50	40	40
Leg to seat surface angle	900	97°	97°
Manoeuvring wheels, diameter	560	610	610
Wheelbase	340	400	400
Camber	-3°	0°	0°
Manoeuvring wheels, horizontal position	20	20	20
Manoeuvring wheels, vertical position	166	184	184
Castor wheels, diameter	150	175	175
Properties of the chassis (se	e NOTE 3)		
Manoeuvring wheels, track	mid-position (see NOTE 4)		
Castor wheels, track	mid-position (see NOTE 4)		
Castor stem housings, horizontal position	mid-position (see NOTE 4)		
Castor stem housings, vertical position	mid-position (see NOTE 4)		
Castor wheel axles, vertical position in fork	mid-position (see NOTE 4)		
Castor rake	0° +1° / -0°		
Castor cant	0° ± 0,5°		

NOTE 1 All dimensions in mm unless otherwise indicated.

NOTE 2 For the purpose of establishing the reference value for the effective seat width use the formula:

$$W = 42 \times \sqrt{M_0} + 35$$

where

 ${\it W}\,$ is the desired width (effective seat width or back support width);

 M_0 is the maximum occupant mass (kg).

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

NOTE 4 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

Table C.3 — Reference set-up values for wheelchairs without handrims (LEVEL 1)

Item Reference set-up valu		alues	
	Occupant mass group	Occupant mass group	Occupant mass group
	I	II	III
	(<50 kg)	(50 kg to 125 kg)	(>125 kg)
Properties of the chassis (see NOTE 1)			
Fixed wheels, diameter	largest diameter		
Fixed wheels, horizontal position	mid-position (see NOTE 2)		
Movable wheels, diameter	largest diameter		
Movable wheels, horizontal position	mid-position (see NOTE 2)		
Castor rake (where applicable)	0° +1° / -0°		
Castor cant (where applicable)	0° ± 0,5°		

NOTE 1 All dimensions in mm unless otherwise indicated.

NOTE 2 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

Table C.4 — Reference set-up values for wheelchairs without handrims (LEVEL 2)

Item	Reference set-up values				
cjick	Occupant mass group I (<50 kg)	Occupant mass group II	Occupant mass group III		
		(50 kg to 125 kg)	(>125 kg)		
Properties for seating and ergonomics (see NOTE 1)					
Seat plane angle	4°	4°	4°		
Effective seat depth	340	450	450		
Effective seat width	In accordance with formula in NOTE 2				
Seat surface height at front edge	470	520	520		
Back support angle	10°	10°	10°		

NOTE 1 All dimensions in mm unless otherwise indicated.

NOTE 2 For the purpose of establishing the reference value for the effective seat width use the formula:

$$W = 42 \times \sqrt{M_{\rm O}} + 55$$

where

W is the desired width (effective seat width or back support width);

 M_0 is the maximum occupant mass (kg).

NOTE 3 When any of these adjustments are in conflict with any seating adjustments, correct the setting to the minimum extent.

NOTE 4 If the mid-position is not available/possible, set as close as possible to the mid-position. If this is not possible (e.g. there are only two positions), set to the position next smaller than the mid-position. If two positions are equally distant from the mid position, set to the smaller of the two.