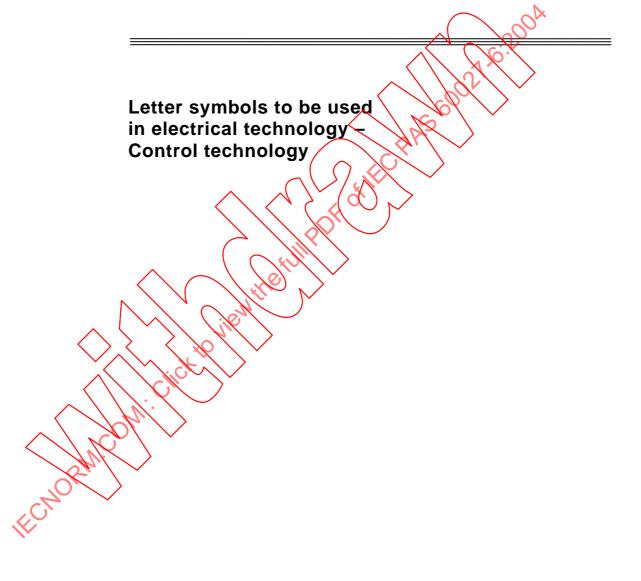
PUBLICLY AVAILABLE SPECIFICATION

IEC PAS 60027-6

First edition 2004-09





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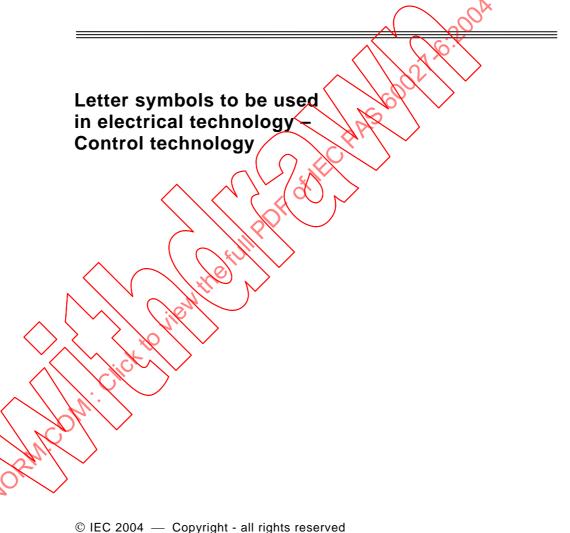
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INTERNATIONAL ELECTROTECHNICAL COMMISSION

LETTER SYMBOLS TO BE USED IN ELECTRICAL TECHNOLOGY – CONTROL TECHNOLOGY

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IEC-PAS 600276 has been processed by IEC technical committee 25: Quantities and units, and their letter symbols.

The text of this PAS is based on the following document:

This PAS was approved for publication by the P-members of the committee concerned as indicated in the following document

Draft PAS	Report on voting
25/271/NP	25/283/RVN

Following publication of this PAS, the technical committee or subcommittee concerned will investigate the possibility of transforming it into an International Standard.

LETTER SYMBOLS TO BE USED IN ELECTRICAL TECHNOLOGY – CONTROL TECHNOLOGY

Introductory note

This Publicly Available Specification (PAS) is intended to replace section 11 of IEC 60027-2:2000.

In comparison to section 11 of IEC 60027-2:2000 the following has been altered.

- The number of physical quantities and of their symbols listed in this PAS has been increased significantly. New sections for general quantities and functions for characteristic quantities of the step response, for parameters of transfer elements and control loops, and for mapping functions and their quantities have been included.
- The hitherto existing series of reserve symbols has been deleted. Four symbols out of this series have been used as new symbols for main quantities.
- The presentation of the denotation of some mathematical concepts specific to the field formerly given in 11.4 has been removed to the column "remarks" of the relevant tables.

1 Scope

This PAS is applicable to control technology. It gives names and symbols for quantities, signals and functions, and their units.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60027-1:1992, Letter symbols to be used in electrical technology - Part 1: General.

IEC 60027-2:2000, Letter symbols to be used in electrical technology – Part 2: Telecommunications and electronics

IEC 60050-101 1998 International Electrotechnical Vocabulary – Part 101: Mathematics

IEC 60050-35 11998, International Electrotechnical Vocabulary – Part 351: Automatic control

ISO 31-2(1992, Quantities and units – Part 2: Periodic and related phenomena

ISO 31-5:1992, Quantities and units – Part 5: Electricity and magnetism.

3 Principles

- **3.1** This PAS presents a coherent body of letter symbols for the most important physical quantities and functions used in control technology science and technology, particularly for important variable quantities and (without distinction) the signals representing them.
- **3.2** Signals and quantities may have any physical form; it is the control engineering design function which characterizes them. Therefore, for most of the quantities and functions listed in this PAS, it is not possible to appoint a special unit to them. For those quantities and functions for which this is possible (1.04 to 1.16, 2.01 to 2.05, 3.04 to 3.15, 5.01, 5.02, and 5.06) any user of this PAS knows the inherent unit.
- 3.3 The names of quantities, functions and signals, their definitions, their 7-digit reference numbers and the names of functional blocks within the functional diagrams are based on IEC 60050-351.
- 3.4 In IEC 60050-101 and IEC 60050-351, letter symbols are just used but not standardized. International standardization of letter symbols and units is to be found in the different parts of ISO 31 and IEC 60027 only.
- 3.5 Any of the basic symbols listed in sections 1 to 5 may be supplemented by the signs and subscripts to be found in IEC 60027-1.
- 3.6 Symbols for time-dependent quantities are covered by EC 60027-1.
- 3.7 Some entries in the column "remarks" give the notation of some mathematical concepts specific to the field.
- 3.8 Vector quantities are represented by the same symbols as the corresponding scalar quantities, but by bold type letters.
- 3.9 The list of recommended letter symbols in sections 1 to 5 is followed in section 6 by functional block diagrams intended to show typical applications.

4 General quantities and functions

Table 1

Item number	Entry number in IEV ¹⁾	Item number in IEC 60027-1	Item number in ISO 31	Name of quantity or function	Symbol	Remarks
4.01	351-21-06			input variable	и	
4.02	351-21-07			output variable	V 2)	
4.03	351-21-08			state variable		Arabic numeral subscripts for components $i = 1, 2, 3,, n$
4.04	101-14-08	18	2-3.1	frequency	X	
4.05	351-24-24	24	2-2	time constant	X FO	
4.06	101-14-36	13	2-4	angular frequency; pulsatance	0)	$\omega = 2\pi f$
4.07	351-28-14			characteristic angular frequency	$>_{\omega_{o}}$	
4.08	351-24-18			damping ratio	${\cal G}$	
4.09	351-24-18		Cienti	eigen angular frèquency; angular frequency of damped oscillation	$\omega_{\sf d}$	$\omega_{\rm d} = \omega_{\rm o} \sqrt{1 - g^2}$
4.10	101-14-20	26	2-11	damping coefficient	δ	$\delta = 9\omega_0$
4.11		19	2-3.2	rotational frequency	f_{r}	
4.12	351-24-37	103	5-43	phase angle	φ	
4.13	101-13-06	953		Dirac function; unit pulse; unit impulse (US)	$\delta(t)$	
4.14	101-13-02	952		unit-step function; Heaviside function	$\varepsilon(t)$	
4.15	351-24-21			unit-step response	h(t)	
4.16	351-24-19			unit-pulse response; unit-impulse response (US); weighting function	g(t)	

As far as the entry number starts with 351, this is the term number in edition 3 of IEC 60050-351 (to be published).

 $^{^{\}rm 2)}~$ The symbol $\,\nu\,$ is a Latin "vee", not a Greek "nu".

5 Characteristic quantities of the step response

Table 2

Item number	Entry number in IEV ³⁾	Name of quantity	Symbol
5.01	351-24-27	equivalent time constant	T_{b}
5.02	351-24-26	equivalent dead-time	T_{e}
5.03	351-24-28	step response time	Psr
5.04	351-24-29	settling time	T_{s}
5.05	351-24-30	overshoot	Contract of the second

6 Parameters of transfer elements and control loops

Table 3

Item number	Entry number in IEV ⁵⁾	Name of quantity	Symbol	Remarks
6.01	351-28-17	proportional action coefficient	K_{P}	Equation of an ideal PID
6.02	351-28-20	integral action	K_{I}	control element: $y(t) = K_{P} u(t) + K_{I} \int_{I}^{t} u(\tau) \mathrm{d}\tau + K_{D} \dot{u}(t)$
6.03	351-28-25	derivative action coefficient	K_{D}	0
6.04	351-28-23	reset time	T_{i}	$T_{i} = K_{P} / K_{I}$
6.05	351-28-28	rate time	T_{d}	$T_{d} = K_{D} / K_{P}$
6.06	351-28-41	dead-time	T_{t}	
6.07	351-25-01	control rise time	T_{cr}	
6.08	351-25-02	control settling time	$T_{\mathtt{cs}}$	
6.09	351-24-40	corner angular frequency	ω_i	<i>i</i> = 1, 2, 3,
6.10	351-25-08	loop gain	K_{o}	
6.11	351-25-08	control factor	R	

 $^{^{3)}}$ The entry number is the term number in edition 3 of IEC 60050-351 (to be published).

For the symbol v see footnote 2. This entry should only determine the index. The main symbol should always be that of the quantity, the overshoot of which is meant.

⁵⁾ See footnote 3.

Item number	Entry number in IEV ⁵⁾	Name of quantity	Symbol	Remarks
6.12	351-25-04	gain crossover angular frequency	ω_{c}	
6.13	351-25-06	phase crossover angular frequency	ω_{π}	
6.14	351-25-05	phase margin	$arphi_{m}$	
6.15	351-25-07	gain margin	G_{m}	
6.16	351-21-17	system matrix	A	General description of a linear
6.17	351-21-15	input matrix	В	system using state variables:
6.18	351-21-16	output matrix	C /	$x \neq Ax + Bu$
6.19	351-21-19	direct input-output matrix	D	v = Cx + Du
6.20	351-21-18	transition matrix	Ø	AP

7 Variable quantities of the control loop 6)

Table 4

Item number	Entry number in IEV 7)	Name of quantity	Symbol	Remarks
7.01	351-27-01	controlled variable	x	
7.02	351-27-02	reference variable	w	
7.03	351-27-03	feedback variable	r	
7.04	351-27-04	error variable	e	e = w - r
7.05	351-27-06	controller output variable	m	
7.062	351-27-07	manipulated variable	У	
2.07	351-27-08	disturbance variable	Z	
7.08	351-27-09	command variable	С	
7.09	351-27-10	final controlled variable	q	

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⁶⁾ Instead of "variable quantities", normally the shorter designation "variables" is used (see IEC 60050-351).

⁷⁾ See footnote 3.

8 Mapping functions and their variable quantities⁸⁾

Table 5

Item Number	Entry number in IEV ⁹⁾	Name of quantity or function	Symbol	Remarks
8.01		mapping variable (quantity) of Laplace transformation	p , s	$p = \sigma + j\omega = -\delta + j\omega = s$
8.02		mapping variable (quantity) of Z transformation	Z	1 26:500
8.03	351-24-31	transfer function	G, F	A function of p or s . In telecommunication, H is used
8.04	351-24-33	frequency response	$G(j\omega)$ $F(j\omega)$	A PA
8.05	351-24-36	gain response: amplitude response	G(jω F(jω	
8.06	351-24-38	phase response	$arg G(j\omega)$ $arg F(j\omega)$	
8.07	351-24-42	describing function	$B(\hat{u})$	A function of the amplitude of the sinusoidal input variable <i>u</i>

NOTE The quantities and functions listed in this table are complex ones. Their symbols may be underlined. If underlined symbols are used for these quantities and functions, the function symbol included in vertical lines has to be used for the gain response.

⁸⁾ See footnote 6.

⁹⁾ See footnote 3.

9 Functional diagrams

NOTE The arrows show the direction of action.

9.1 Open-loop control system; guidance system

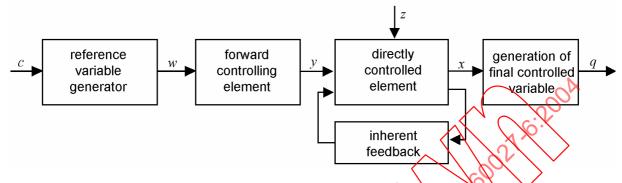


Figure 1 - Open-loop control system; guidance system

9.2 Closed-loop control system; feedback control system

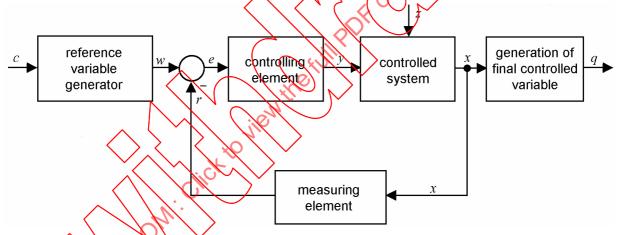


Figure 2 - Closed-loop control system; feedback control system

9.3 System description using state variables

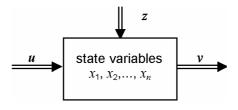


Figure 3 – System description using state variables¹⁰⁾

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¹⁰⁾ See footnote 2.